#### High Performance Iterative Methods using Accurate Computations

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# Accelerate Iterative Methods

- Good Algorithms
- Good Preconditioners
- Parallel Algorithms
- Good Implementations
- Accurate Computations

# Accelerate Iterative Methods

- Good Algorithms Need Innovation
- Good Preconditioners
   Need Innovation
- Parallel Algorithms More iterations or low performance
- Good Implementations Depends on Hardware and Data Structure
- Accurate Computations High Cost

# Problem

- Theoretically Krylov methods converge at most n iterations
- Divergence or Stagnation occurs because of round-off errors



#### Answer

- To improve convergence, High-precision arithmetic operations are effective.
- However they are costly, real \*16 of Fortran:
  - memory: Double
  - comp.: 20 times





#### Our Solution: Utilize Accurate Computations for Iterative Methods

- Use Double-double
- Use D-D vectors and Double Matrices (Mixed Precision Arithmetic Operations)
- Use SSE and AVX
- Restart with different Precision

# Advantages

- Tough for round-off errors
- Small Additional Memory
- Small Additional Communications
- Much Computations
- Applicable for **ALL** Iterative Methods (even if serial computation such as ILU)

Implementation of Double-double Arithmetic

- Quadruple value is stored in two double floating point numbers
  - Double-double arithmetic: a = a.hi + a.lo, |a.hi|>|a.lo|
  - 8 bits less than IEEE standards
  - Effective digits are approx. 31 vs. 33 digits.

double-double arithmetic

exponent 11 bit	Mantissa 52bit	+	Exponent 11bit	Mantissa 52 bit

**IEEE** Standards

exponent 15bit	ICL lunch talk at March 16, 2012	
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#### Round-off Error Free Double Arithmetic Addition

- Round-off error free addition can be done with two double precision variables:
   a + b = fl(a + b) + err(a + b)
  - a,b: double floating point variables
     fl(a + b) : addition of a and b in double
     err(a+b): (a+b) fl(a+b): error

#### **Basic Algorithm**

Dekker showed round-off error free
 addition in double

|a| > = |b| 3flops. Others 6flops. FAST TWO SUM(a,b,s,e) TWO SUM(a,b,s,e) s = a + bs = a + be = b - (s - a)v = s - ae = (a - (s - v)) + (b - v)а b S b s-a а S е S-&CL lund rch 16, 2012

#### Quadruple Addition of a=b+c

b.hi b.lo 🕂 c.hi c.lo	b.hi b.lo	+	c.hi	c.lo	
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A. TWO\_SUM for upper parts

b.hi	+	c.hi	=	sh	eh
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B. Addition of lower parts



## Quadruple Addition of a=b+c

ADD(a,b,c) 20 flops
TWO\_SUM(b.hi,c.hi,sh,eh)
TWO\_SUM(b.lo,c.lo,sl,el)
eh = eh + sl
FAST\_TWO\_SUM(sh,eh,sh,eh)
eh = eh + el
FAST\_TWO\_SUM(sh,eh,a.hi,a.lo)

#### a=(a.hi,a.lo), b=(b.hi,b.lo), c=(c.hi,c.lo)

# Design of Fast Quad. Operations for Lis (a Library of Iterative Solvers for linear systems)

- Same API with Double
- Double: Input (A, b,  $x_0$ )
- Double: Output
- Double: Creation of Preconditioner M
- Fast Quad.: Iterative solution x All working variables
- Fast Quad.: Application of Preconditioner Mu=v

# Implementation

- Replace Double to Fast Quadruple Arith. Op.
  - Matrix-vector product(matvec)
  - Inner product(dot)
  - Vector operation(axpy)
- Use multiply-and-Add for matvec, dot, axpy
  - Reduce memory access, especially store
- Make two Multiply-and-Add functions
  - FMA (Fast Quadruple) for dot and axpy require 33 double flops
  - FMAD (Double and Fast Quadruple) for matvec require 29 double flops

# Acceleration by SSE2/AVX

- SSE2 is used for vectors (dot, axpy, matvec)
   2 Multiply-and-add in same time
- Two FMA in a loop with loop unrolling
   pd instruction of SSE2 can be used for all
- Code tuning
  - Alignment
  - Some hand optimization





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#### Convergence History of A4 with Preconditioned BiCG



### **Result of Problem A4**

Pre.	re. Double		ole	Fa	druple	
	sec.	iter.	TRR	sec.	iter.	TRR
BiCG         Jacobi       26.58       1833       7.68E-15         ILU(0)       20.41       460       1.25E-14         SSOR       29.78       642       1.27E-14         ILUC       17.78       350       1.13E-14						
Jacobi				26.58	1833	7.68E-15
ILU(0)				20.41 460 1		1.25E-14
SSOR				29.78	642	1.27E-14
ILUC				17.78	350	1.13E-14
		-	GPBiC	G		
Jacobi				34.50	1403	6.89E-15
ILU(0)	2.99	407	1.91E-14	18.43	225	1.17E-14
SSOR				42.53	500	1.02E-14
ILUC	11.71	364	1.67E-14	25.95	274	3.05E-15

Mixed Precision Iterative Methods Combination of Double and Fast Quadruple

Lis QUAD: Fast Quadruple Arithmetic

- Improve convergence! Make robust!
- Excessive quality
- Still Costly x 3.2 on Xeon, x 3.1 on Core2 Duo

Reduce computation time

→ Reduce Quadruple Operations

#### **Basic Idea of Restart**

• Until Now:

(1)Solve  $Ax^* = b$  with some initial value  $x_0$ 

(2)Solve Ax=b with an initial value  $x^*$ 

- In general, (1) and (2) have same spaces, same methods, and same precisions
- (1) and (2) have same spaces, same methods but different precisions
   (combination of Double and Fast Quadruple).

### SWITCH Algorithm

- Restart with different precision arithmetic
  - Current solution xk is passed at the restart
  - Upper and Lower part of Double-Double var. are stored in different arrays
  - Only Upper part is used for
     Double Precision
  - Two Stages are performed by Different Precisions

```
for(k=0;k<matitr;k++){
    The first step
    if( nrm2<restart_tol ) break;
}
Clear all values except x
for(k=k+1;k<maxtr;k++) {
    The second step
    if( nrm2<tol ) break;
}</pre>
```

		ite	r.		
a ir	fo i <u>l 2</u> d	total	doub le	sec.	b-A x
DOUBLE		4567	4567	18.64	3.25E-08
QUAD		3838		69.39	5.36E-10
SW ITCH	ε =1.0E-10	4402	4091	24.25	3.15E-10
	ε=1.0E-11	4331	4176	21.66	3.13E-10
	ε=1.0E-12	4709	4567	22.87	3.56E-10
W	ang3	total	doub e	sec.	b-A x
DOUBLE		476	476	2.03	<u>3.52E-10</u>
QUAD		372		7.31	1.49E-10
SW ITCH	ε=1.0E-10	460	361	3.67	1.59E-10
	ε=1.0E-11	459	444	2.42	9.22E-11
	ε=1.0E-12	479	476	2.32	1.46E-10
an	guage	total	doub e	sec.	b-A x
DOUBLE		39	39	3.42	2.96E-09
QUAD		36		10.53	4.25E-11
SW ITCH	ε=1.0E-10	38	34	4.57	1.71E-10
	ε=1.0E-11	37	35	4.07	4.20E-10
	ε=1.0E-12	40	39	4.18	4.47E-10

 $-\epsilon$  is restaring criterion of SWITCH

• QUAD and SWITCH improve 2 digits for solution' quality

• SWITCH is 20% overhead on a the double, however robust

# Circuit\_3, BiCG with ILU(0)



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#### Computation Time Poisson (n=10^6, CRS), Xeon 2.8GHz



#### Auto Restart with Different Precisions

• Convergent history shows three patterns:



#### Auto Restart of DQ-SWITCH

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 Compute deviation of residual norm

$$v = \frac{1}{p} \sum_{i=1}^{p} \left( \frac{nrm(i) - nrm(1)}{nrm(1)} \right)$$

• (D)  $v \ge 10^2$ 

• (S)  $v \le 10^{-1}$ 

```
if( nrm2 < nrm2_min )
   nrm2 min = nrm2; x bak = x;
nrm_bak[k\%10] = nrm2;
if( k>=10 ) {
  v = 0.0; c = 0;
  for(i=0;i<10;i++) {
   t = nrm_bak[i] - nrm_bak[(k-9)%10];
   t = t / nrm_bak[(k-9)%10];
   v = v + t^{*}t;
   if( nrm_bak[(k-9)%10] <= nrm_bak[i] )
     c = c+1:
  v = v / 10;
  if( v<=0.1 || (c==10 && v>=100) ) break;
  if( nrm2<tol ) break;
```

# Electoronics BiCG with ILU(0)



- Divergence or Stagnation is detected.
- Computation time is reduced. ICL lunch talk at March 16, 2012

# Parallel Issues for Fast Quad.

- Depends on the implementation of Ax, A<sup>T</sup>x, M<sup>-1</sup>x, M<sup>-T</sup>x, and Matrix Storage Format
- Data transfered is almost same
- Heavy Computation
  - $\rightarrow$  Suitable for Distributed Parallel
- Less round-off errors
  - → lighter preconditioner (easy to parallelize)

#### 50 BiCG Iterations on Distributed Parallel

# of PEs	Double	Fast Quadruple
1	7.56sec	24.21sec
2	3.90sec(1.93)	12.22sec(1.98)
4	2.02sec(3.74)	6.23sec(3.88)
8	1.11sec(6.87)	3.18sec(7.61)

#### Computation Time Poisson (n=10^6, CRS), Xeon 2.8GHz



\*3.74 \*6.84 \*3.88 \*7.61

# Conclusion

- Fast Quadruple Arithmetic Operations using SSE2
  - Reduce round-off errors
  - Computation time is about 3.2 times of Double
- Mixed Precision Iterative Methods
  - Combine Double and Fast Quadruple
  - DQ-SWITCH is faster for complecated problems (Double does not converge!)
  - DQ-SWITCH is robust but costly for ordinary problems
  - Overhead is 20%
  - Automatic Restart
- These methods fit for Parallel computing environments.
- Lighter preconditioners should be effective for parallel environments

# SILC: Simple Interface for Library Collections

- Basic ideas
  - Data transfer and a request for computation
  - Mathematical expressions for the request
  - A separate memory space for the computation



# Solving a system of linear equations Ax = b

In the traditional way (using LAPACK in C)

```
double *A, *b;
int kl, ku, lda, ldb, nrhs, info, *ipiv;
dgbtrf (N, N, kl, ku, A, lda, ipiv, &info); /* LU factorization */
if (info == 0)
    dgbtrs ('N', N, kl, ku, nrhs, A, lda, ipiv, b, ldb, &info); /* solve */
```

In SILC

```
silc_envelope_t A, b, x;
SILC_PUT ("A", &A);
SILC_PUT ("b", &b);
SILC_EXEC ("x = A \ b"); /* call a solver (e.g., dgbtrf & dgbtrs) */
SILC_GET (&x, "x");
```

# Main benefits of using SILC

- Source-level independence between user programs and matrix computation libraries
  - Easy access to alternative solvers and matrix storage formats, possibly in other libraries
  - Instant porting to other computing environments without any modification in user programs
- You need to prepare only the smallest amount of data
  - Temporary buffers are automatically allocated
- Language-independent mathematical expressions
  - Applicable in many programming languages (C, Fortran, Python, MATLAB)



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#### SILC servers in different computing environments

- A user program (client) that solves Ax = b
  - Where A is a tridiagonal matrix in the CRS format
  - Run in the notebook PC of Environment (a)
  - In a 100-Base TX local-area network

	Environment	Specification	OpenMP	
(a)	A notebook PC	Intel Pentium M 733 1.1GHz, 768MB memory, Fedora Core 3	N/A	C – S
(b)	SGI Altix3700	Intel Itanium2 1.3GHz × 32, 32GB memory, Red Hat Linux Advanced Server 2.1	1 thread	C S
(c)	IBM eServer OpenPower 710	IBM Power5 1.65GHz × 2 (4 logical CPUs), 1GB memory, SuSE Linux Enterprise Server 9	4 threads	C S
(d)	SGI Altix3700	Same as (b)	16 threads	
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## **Experimental results**

- About 0.1 second of data communications over the LAN
   Data size: 0.46MB (N=10,000) to 4.27MB (N=80,000)
- SILC servers in (c) and (d) achieved better performance because of parallel computation



# Functionalities of SILC

- Data structures
  - Data types: scalar, vector, matrix, cubic array
  - Precisions: integer, real, complex (single or double)
  - Matrix storage formats: dense, banded, CRS
- Mathematical expressions
  - Binary arithmetic operators (+, -, \*, /, %)
  - Solutions of systems of linear equations (A\b)
  - Conjugate transposes (A'), complex conjugates (A~)
  - Built-in functions
    - Ex. "sqrt(b' \* b)" is the 2-norm of vector b
  - Subscript
    - Ex. "A[1:5,1:5]" is a 5×5 submatrix of A

## Modes for using LAPACK in SILC

#### Mode (A)

 Both data transfer and computation with LAPACK

#### Mode (B)

- Data transfer with LAPACK
- Computation with another library

#### Mode (C)

- Data transfer with another library
- Computation with
   LAPACK



# Lis-test for evaluation

- Over 2K combinations: 10 Preconditioners x 13 Solvers x 11 Storage formats x 2 precisions
- Run on Windows from USB not to install.
- Prepare Matrix data as text file with Matrix Market' exchange format
- May use data located in Web page
- Run in parallel if the PC has multi-cores
- To click, solutions, history, etc are computed

🏭 Lis-test for wind	ows 0.1											
Matrix A C:¥Document RHS b ● File ● 1 Dimension: 37 Nonzeros : 54 Include b: Ye Solvers ■ CG ■ BiCG ■ BiCGSTAB ■ GPBiCG ■ BiCGSTAB ■ GPBiCG ■ BiCGSafe ■ TFQMR ■ Jacobi ■ Gauss-Seidel ■ SOR w = 1.9	ts and Settings¥hasega b=(1,,1) <sup>°</sup> T ○ b=A * ( 7054 × 37054 44430 es □ CR □ CR □ BiCR □ BiCR □ BiCRSTAB □ GPBiCR □ BiCRStAB □ BiCRStAB() □ GMRES(m) □ GMRES(m) □ FGMRES(m) □ ORTHOMIN(m)	v <u>O</u> 11 O AL m = m = m = H	pen )^T pen L 2 40 40 40 40	Cance	3	Cor   rk  Stor Prec	nditions —  2/  r0  2 < cision conditione Jacobi ILU(k) ILUT Crout ILU SSOR Hybrid I+S SAINV SA-AMG	(=  1.0e-  CRS  Quadru ers k = dro dro tol m : dro	012 ple • ple • 0 p = 0.1 p = 0.1 R = 1.0e = 3 p = 0.1	MaxIters = Block Size # of Thread Al rate = rate = ww = =003 MaxIt alpha	1000 = 2 ds 1 .L CLE : 10.0 : 10.0 : 10.0 : 1.5 er= 25 = 1.0	- AR
Solver	Precon	Ρ	Т	Iter.	Sec	D.	p_cre	p_sol	i_sol	TRR	Stora	Opt
RDY bicg RDY gpbicg RDY bicr RDY gpbicr	Lis-test		1 1 1	UI	fo	or	Lib	orar	y L	_is	CRS CRS CRS CRS	"C3 "C3 "C3
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### Comparison is done easily!



#### Features of Lis:

a Library of Iterative Solvers for linear systems

• Over 2K combinations:

10 Preconditioners x 13 Solvers x 11 Storage formats x 2 precisions

- 4 computing environments
  - Serial
  - OpenMP for Shared memory
  - MPI for Distributed memory
  - Hybrid of OpenMP and MPI
- Fast quadruple arithmetic operations
- Same interface with Double/Quadruple

#### To get code and more

#### Visit the SILC and Lis home pages:



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